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## **ABSTRACT**

A data processing system blind source separation of an overcomplete set of signals generally includes means for storing input from sensors in a mixed signal matrix X 200, noise in a noise matrix Y 202, an estimate of the individual signals from the mixture of signals from the signal sources in a source signal estimate matrix  $\hat{S}$  204, and an estimate of environmental effects in a mixing matrix  $\hat{A}$  206, the matrices related by  $X = \hat{A}\hat{S} + V$ ; generating an initial estimate of  $\hat{A}$  208; determining the number of, and associated lines of correlation of, each source from  $\hat{A}$ , and representing the sources in the source signal estimate matrix  $\hat{S}$  210; jointly optimizing  $\hat{S}$  and  $\hat{A}$  in an iterative manner to generate an optimized source signal estimate matrix  $\hat{S}$  212 and a final estimated mixing matrix  $\hat{A}$ ; and restoring the separated source signals from the optimized source signal estimate matrix  $\hat{S}$  214.